

Korea HDV CO₂ regulation

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Ministry of Environment, Korea

National Institute of Environmental Research



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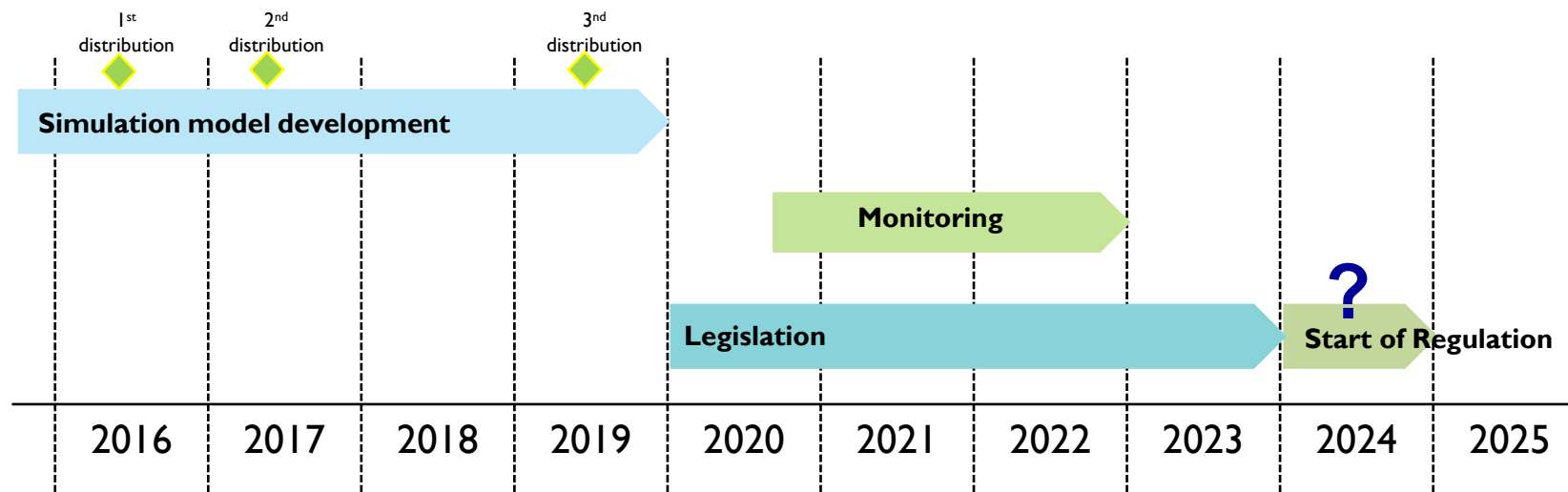
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Regulatory Timeline(Proposed Rule)



- **Simulation program development**

- Simulation model distribution to manufacturer (1st distribution in 2016, 2nd in 2017, 3rd in 2019)

- **Monitoring (3Q, 2020~), Legislation**

CO₂ emission monitoring, Set CO₂ reduction target, super credit, eco innovation technology

- **Start of Regulation (2025 ~)**



Simulation model: HES, Heavy-duty vehicle Emission Simulator

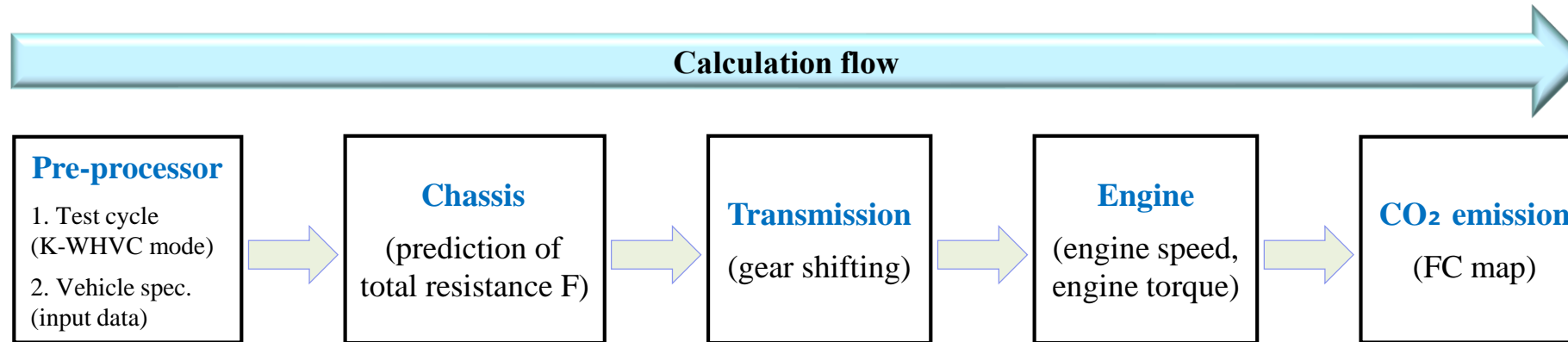


Fig. Basic model structure

○ Vehicle dynamic based simulation model for MHDVs (Medium and Heavy Duty Vehicles) in Korea

➤ MHDVs simulation model (Korea): Composed of five components as follow:



1. **Pre-processor module:** reading input data (vehicle specifications and velocity profile)
2. **Chassis module:** calculating total resistance force acting on vehicle
3. **Transmission module:** predicting gear position at each time step based on engine operating condition
4. **Engine module:** determining engine torque & speed at each time step
5. **CO₂ emission module:** predicting CO₂ emission based on fuel map & CO₂ emission factor of fuel

○ Backward type calculation program (wheel to engine)



Simulation model: HES, Heavy-duty vehicle Emission Simulator

- HES Engine power calculation model

	Item	Calculation	Remark
1	Acceleration	$P_{acc} [kW] = \text{Weight [kg]} * \text{acceleration [m/s}^2] * \text{velocity [m/s]} * 0.001$	
2	Load inclination	$P_{slope} [kW] = \text{Weight [kg]} * 9.81 [m/s^2] * \text{gradient}(\sin\theta) * \text{velocity [m/s]} * 0.001$	
3	Air drag	$P_{air} [kW] = 0.5 * \text{density [kg/m}^3] * \text{CdA [m}^2] * \text{velocity}^3 [m/s] * 0.001 * \text{Correction factor}$	density = 1.188 kg/m ³
4	Rolling resistance	$P_{roll} [kW] = \text{RRC [-]} * \text{Weight [kg]} * \text{velocity [m/s]} * 0.001$	
5	Auxiliary	$P_{aux} [kW] = \text{auxiliary power demand [kW]}$	Default data
6	Engine rotational inertia	$P_{inertia_engine} [kW] = \text{engine inertia [kg*m}^2] / \text{tire radius}^2 [m] * \text{acceleration [m/s}^2] * \text{velocity [m/s]} * 0.001$	Default data
7	Tire rotational inertia	$P_{inertia_wheel} [kW] = \text{tire inertia [kg*m}^2] / \text{tire radius}^2 [m] * \text{acceleration [m/s}^2] * \text{velocity [m/s]} * 0.001$	
8	Transmission loss	$P_{transmission_loss} [kW] = \text{Transmission torque loss [Nm]} * \text{engine speed [rpm]} * \frac{2\pi}{60} * 0.001$	Default data
9	Axle loss	$P_{axle_loss} [kW] = \text{Axle Torque loss [Nm]} / \text{transmission ratio [-]} * \text{engine speed [rpm]} * \frac{2\pi}{60} * 0.001$	Default data
10	Retarder loss	$P_{retarder_loss} [kW] = \text{Retarder torque loss [Nm]} / \text{transmission ratio [-]} * \text{engine speed [rpm]} * \frac{2\pi}{60} * 0.001$	Default data
Sum	Engine power	$P_{eng} [kW] = P_{acc} [kW] + P_{slope} [kW] + P_{air} [kW] + P_{roll} [kW] + P_{aux} [kW] + P_{inertia_engine} [kW] + P_{inertia_wheel} [kW] + P_{transmiss_loss} [kW] + P_{axle_loss} [kW] + P_{retarder_loss} [kW]$	



Test cycle (target velocity)

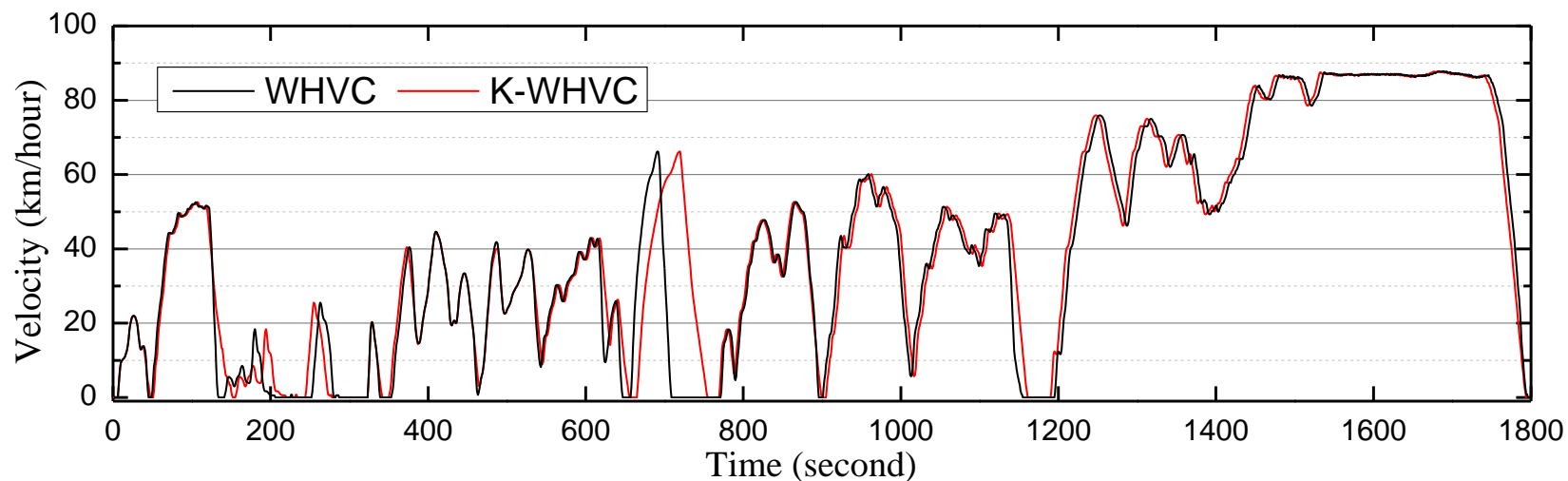


Fig. Comparison of original WHVC and K-WHVC mode (velocity profile)

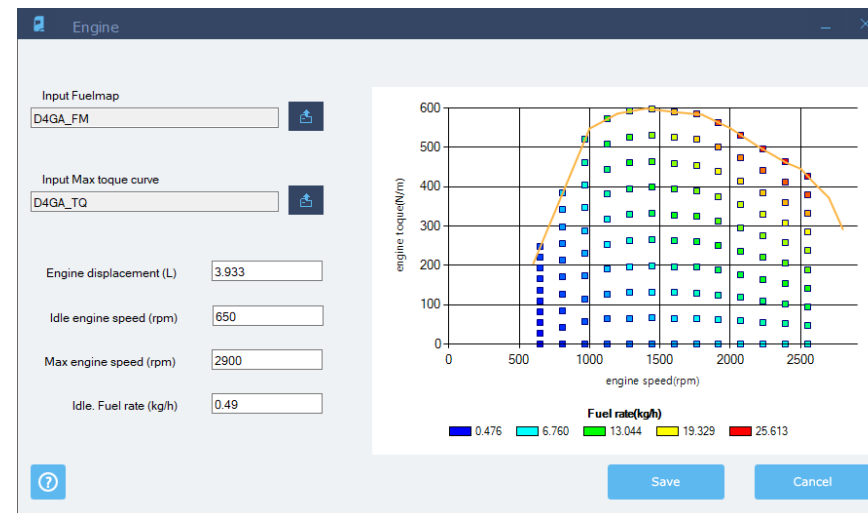
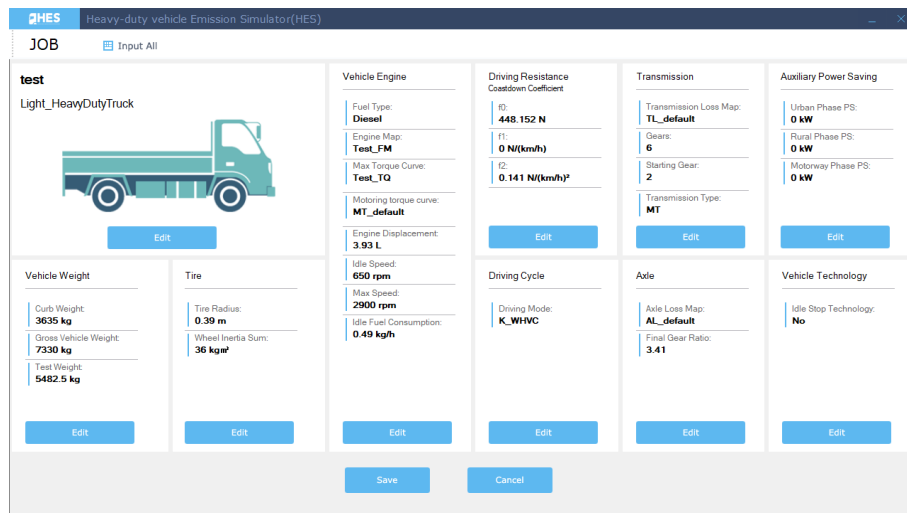
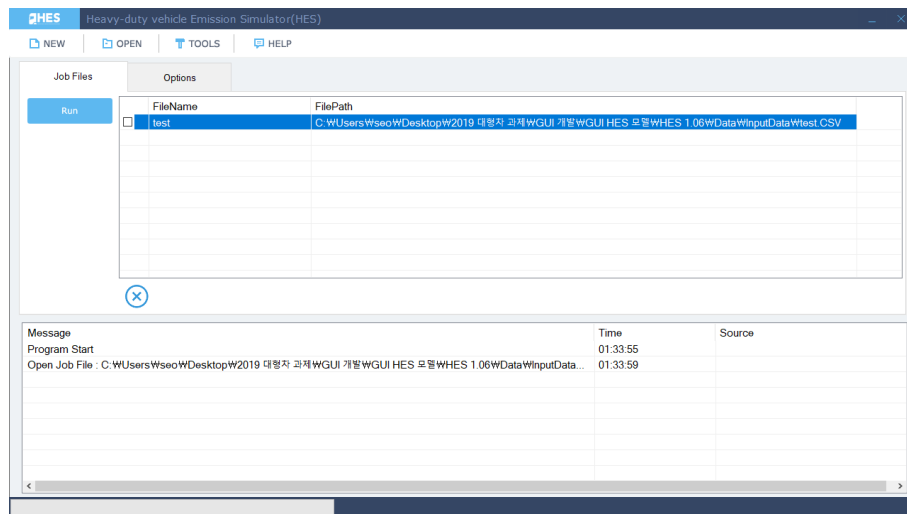
○ Modification of WHVC driving mode

- WHVC mode represents real driving pattern of MHDVs in Korea reasonably
- However, **some HDVs (GVW>30 ton) are not able to follow the WHVC** in specific acceleration regions

➡ **K-WHVC** driving cycle had been developed to **enhance a correlation between simulation and test results**



HES interface





HES interface

HES result file(.pdf)

raw file(.csv)

test1

Input Data Date / Time : 2019.10.24 08:39

Vehicle type : Light_HeavyDutyTruck



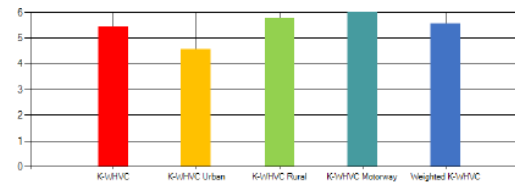
Vehicle type	Light_HeavyDutyTruck
Transmission type	MT
Curb weight [kg]	3635
GVW [kg]	7330
f0 [N] (RRR-test weight*9.8)	448.152
f1 [N/(km/h)]	0
f2 [N/(km/h) ²] (0.5*1.188*CdA/3.6 ²)	0.141
Engine displacement [L]	3.93
Max. gear position	6
Tire radius [m]	0.39
Fuel Type	Diesel
Fuel map	Test_FM
Max TQ curve	Test_TQ

test1

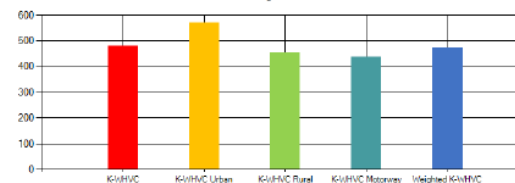
Result Date / Time : 2019.10.24 08:39

	Fuel_economy[km/L]	CO2 [g/km]
K-WHVC	5.452	480
K-WHVC Urban	4.576	572
K-WHVC Rural	5.765	454
K-WHVC Motorway	5.989	437
Weighted K-WHVC	5.559	470.8

Fuel economy (km/L)



CO2(g/km)



1/2

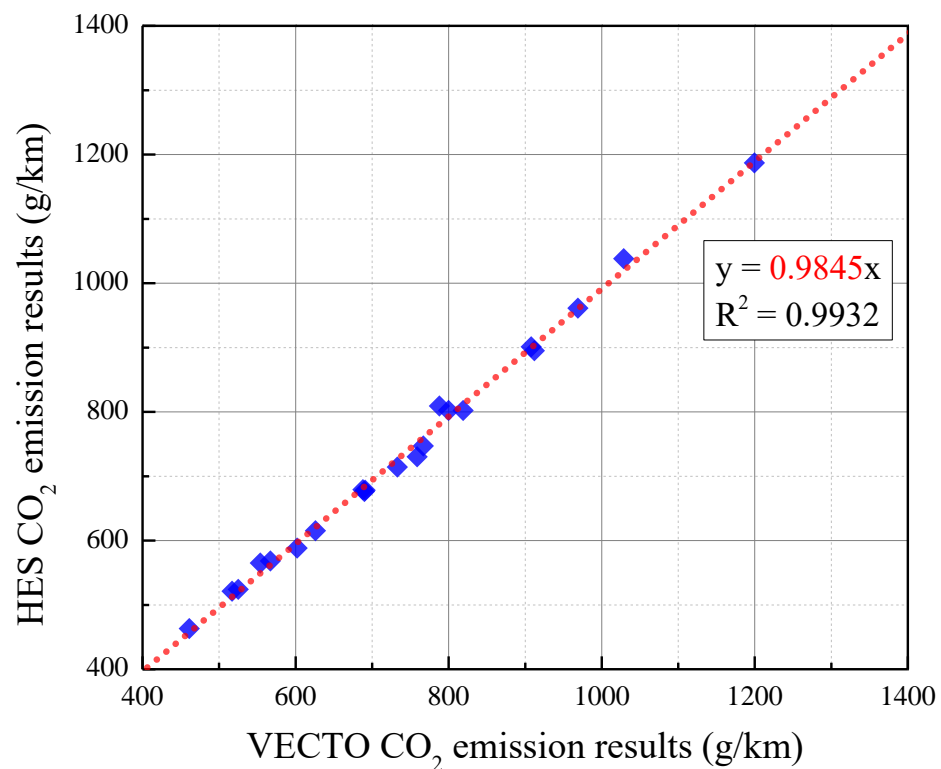
2/2

Case1.csv - Excel

	A	B	C	D	E	F	G	
	Time[s]	Mode_spd	V_spd[km/h]	Road slop	EG_spd[RF]	EG_tq[Nm]	Gear[-]	Fue
1	0	0	0	0	650	56.41431	0	0
2	1	0	0	0	650	56.41431	0	0
3	2	0	0	0	650	56.41431	0	0
4	3	0	0	0	650	56.41431	0	0
5	4	0	0	0	650	56.41431	0	0
6	5	0	0	0	650	56.41431	0	0
7	6	0	0	0	650	56.41431	0	0
8	7	2.35	2.35	0	751.25	68.08828	0	1.
9	8	5.57	5.57	0	751.25	161.4478	2	2.
10	9	8.18	8.18	0	751.25	253.619	2	3.
11	10	9.37	9.37	0	844.7629	171.1437	2	3.
12	11	9.86	9.86	0	888.9394	122.0023	2	2.
13	12	10.18	10.18	0	917.7894	108.8083	2	2.
14	13	10.38	10.38	0	935.8206	99.48227	2	2.
15	14	10.57	10.57	0	952.9502	98.17267	2	2.
16	15	10.95	10.95	0	987.2096	110.8321	2	3.
17	16	11.56	11.56	0	1042.205	125.6491	2	3.
18	17	12.22	12.22	0	1101.708	127.7736	2	4.
19	18	12.97	12.97	0	1169.325	132.7551	2	4.
20	19	14.33	14.33	0	1291.937	172.863	2	6.
21	20	16.38	16.38	0	1476.757	217.332	2	8.
22	21	18.4	18.4	0	1658.873	215.2251	2	10.
23	22	19.86	19.86	0	1790.501	177.4331	2	10.
24	23	20.95	20.95	0	1855.227	221.7087	2	5.



Correlation analysis between HES and VECTO



$$\frac{\text{HES CO}_2 \text{ emissions}}{\text{VECTO CO}_2 \text{ emissions}} = 0.9845$$

$$R^2 = 0.9932$$

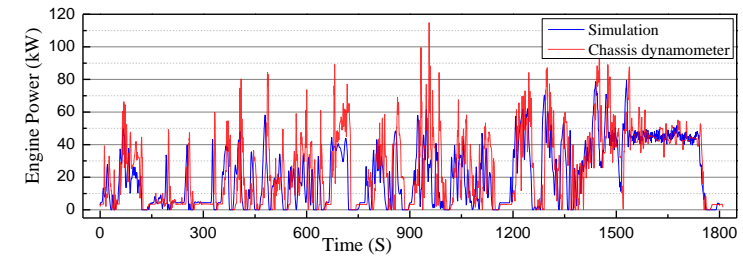
- 42 cases of input data are simulated in HES and VECTO
- HES results are very similar to VECTO results



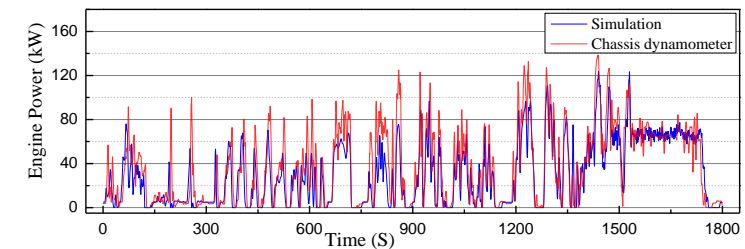
Chassis dynamometer test

Type	GVW	Max payload	Engine	Model year	Chassis dynamo result (g/km)	HES result (g/km)	Error (%)
Truck	39 ton	25 ton	12.7 L	2011	853	909	6.5
Truck	7.2 ton	2.5 ton	3.9 L	2017	339 357 359	371	3.7
Truck	10.4 ton	3.5 ton	6.3 L	2017	476 508 511	522	4.7
Bus	14.8 ton	54 passenger	11.6 L (CNG)	2016	596 598 600	599	0.2

Engine power (7 ton truck)



Engine power (10 ton truck)



- HES result validation with chassis dynamometer results
- About average error: 5%



HDV CO₂ Monitoring and legislation

- 2020~: CO₂ emission monitoring for rigid trucks (including tractors and buses)
 - Considering phased obligation rate with regard to the monitoring and reporting timetable for each type of category
- 2022~: Legislation process
 - Determination of CO₂ reduction rate

Thanks for your attention

Please Contact, If you have question about HES

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